# The C++ Programming Language

# Single and Multiple Inheritance in C++

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# Background

- Object-oriented programming is often defined as the combination of Abstract Data Types (ADTs) with Inheritance and Dynamic Binding
- Each concept addresses a different aspect of system decomposition:
  - 1. ADTs decompose systems into *two-dimensional* grids of modules
    - Each module has *public* and *private* interfaces
  - 2. Inheritance decomposes systems into *three-dimensional* hierarchies of modules
    - Inheritance relationships form a "lattice"
  - 3. Dynamic binding enhances inheritance
    - *e.g.*, defer implementation decisions until late in the design phase or even until run-time!

Data Abstraction vs. Inheritance



# **Motivation for Inheritance**

- Inheritance allows you to write code to handle certain cases and allows other developers to write code that handles more specialized cases, while your code continues to work
- Inheritance partitions a system architecture into semi-disjoint components that are related hierarchically
- Therefore, we may be able to modify and/or reuse sections of the inheritance hierarchy without disturbing existing code, *e.g.*,
  - Change sibling subtree interfaces
    - \* *i.e.*, a consequence of inheritance
  - Change implementation of ancestors
    - \* *i.e.*, a consequence of data abstraction

## Inheritance Overview

- A type (called a *subclass* or *derived* type) can inherit the characteristics of another type(s) (called a *superclass* or *base type*)
  - The term *subclass* is equivalent to *derived type*
- A derived type acts just like the base type, except for an explicit list of:
  - 1. Specializations
    - Change implementations without changing the base class interface
      - Most useful when combined with dynamic binding
  - 2. *Generalizations/Extensions* 
    - Add new operations or data to derived classes

# **Visualizing Inheritance**



# **Types of Inheritance**

- Inheritance comes in two forms, depending on number of *parents* a subclass has
  - 1. Single Inheritance (SI)
    - Only one parent per derived class
    - Form an inheritance "tree"
    - SI requires a small amount of run-time overhead when used with dynamic binding
    - e.g., Smalltalk, Simula, Object Pascal
  - 2. *Multiple Inheritance* (MI)
    - More than one parent per derived class
    - Forms an inheritance "Directed Acyclic Graph" (DAG)
    - Compared with SI, MI adds additional runtime overhead (also involving dynamic binding)
    - e.g., C++, Eiffel, Flavors (a LISP dialect)

# Inheritance Trees vs. Inheritance

#### DAGs



# **Inheritance Benefits**

- 1. Increase reuse and software quality
  - Programmers reuse the base classes instead of writing new classes
    - Integrates *black-box* and *white-box* reuse by allowing extensibility and modification without changing existing code
  - Using well-tested base classes helps reduce bugs in applications that use them
  - Reduce object code size
- 2. Enhance extensibility and comprehensibility
  - Helps support more flexible and extensible architectures (along with dynamic binding)
    - *i.e.*, supports the open/closed principle
  - Often useful for modeling and classifying hierarchicallyrelated domains

# Inheritance Liabilities

- May create deep and/or wide hierarchies that are hard to understand and navigate without class browser tools
- 2. May decrease performance slightly
  - *i.e.*, when combined with *multiple inheritance* and *dynamic binding*
- 3. Without dynamic binding, inheritance has only limited utility
  - Likewise, dynamic binding is almost totally useless without inheritance
- 4. Brittle hierarchies, which may impose dependencies upon ancestor names

# Inheritance in C++

- Deriving a class involves an extension to the C++ class declaration syntax
- The class head is modified to allow a *derivation list* consisting of base classes
- e.g.,

```
class Foo { /* ... };
class Bar : public Foo { /* ... };
class Foo : public Foo, public Bar { /* ... };
```

# Key Properties of C++

## Inheritance

- The base/derived class relationship is explicitly recognized in C++ by predefined standard conversions
  - *i.e.*, a pointer to a derived class may always be assigned to a pointer to a base class that was inherited *publically*
    - \* But not vice versa...
- When combined with dynamic binding, this special relationship between inherited class types promotes a type-secure, *polymorphic* style of programming
  - *i.e.*, the programmer need not know the actual type of a class at compile-time
  - Note, C++ is not truly polymorphic
    - *i.e.*, operations are not applicable to objects that don't contain definitions of these operations at some point in their inheritance hierarchy

# Simple Screen Class

• The following code is used as the base class:

```
class Screen {
public:
     Screen (int = 8, int = 40, char = ' ');
     ~Screen (void);
     short height (void) const { return this->height_; }
     short width (void) const { return this->width_; }
    void height (short h) { this->height_ = h; }
    void width (short w) { this->width_ = w; }
     Screen & forward (void);
     Screen &up (void);
     Screen & down (void);
     Screen & home (void);
     Screen & bottom (void);
     Screen & display (void);
     Screen & copy (const Screen &);
     // ...
private:
     short height_, width_;
     char *screen_, *cur_pos_;
};
```

# Subclassing from Screen

- class Screen can be a public base class of class Window
- e.g.,

```
class Window : public Screen {
  public:
    Window (const Point &, int rows = 24,
        int columns = 80,
        char default_char = ' ');
  void set_foreground_color (Color &);
  void set_background_color (Color &);
  void resize (int height, int width);
    // ...
private:
    Point center_;
    Color foreground_;
    Color background_;
    // ...
};
```

## **Multiple Levels of Derivation**

• A derived class can itself form the basis for further derivation, *e.g.*,

```
class Menu : public Window {
public:
    void set_label (const char *I);
    Menu (const Point &, int rows = 24,
        int columns = 80,
        char default_char = ' ');
    // ...
private:
    char *label_;
    // ...
};
```

- class Menu inherits data and methods from both Window and Screen
  - i.e., sizeof (Menu) >= sizeof (Window) >= sizeof (Screen)

## **The Screen Inheritance Hierarchy**



• Screen/Window/Menu hierarchy



 A pointer to a derived class can be assigned to a pointer to any of its *public* base classes without requiring an explicit cast:

Menu m; Window &w = m; Screen \*ps1 = &w; Screen \*ps2 = &m;

# Using the Screen Hierarchy

```
• e.g.,
```

```
class Screen { public: virtual void dump (ostream &); = 0 }
class Window : public Screen {
    public: virtual void dump (ostream &);
};
class Menu : public Window {
    public: virtual void dump (ostream &);
};
// stand-alone function
void dump_image (Screen *s, ostream &o) {
    // Some processing omitted
    s->dump (o);
    // (*s->vptr[1]) (s, o));
}
Screen s; Window w; Menu m;
Bit_Vector bv;
// OK: Window is a kind of Screen
dump_image (&w, cout);
// OK: Menu is a kind of Screen
dump_image (&m, cout);
// OK: argument types match exactly
dump_image (&s, cout);
// Error: Bit_Vector is not a kind of Screen!
dump_image (&bv, cout);
```

# Using Inheritance for Specialization

- A derived class *specializes* a base class by adding new, more specific *state variables* and *methods* 
  - Method use the same interface, even though they are implemented differently

\* *i.e.*, "overridden"

- Note, there is an important distinction between overriding, hiding, and overloading...
- A variant of this is used in the *template method* pattern
  - *i.e.*, behavior of the base class relies on functionality supplied by the derived class
  - This is directly supported in C++ via abstract base classes and pure virtual functions

# **Specialization Example**

- Inheritance may be used to obtain the features of one data type in another closely related data type
- For example, class Date represents an arbitrary Date:

```
class Date {
public:
    Date (int m, int d, int y);
    virtual void print (ostream &s) const;
    // ...
private:
    int month_, day_, year_;
};
```

 Class Birthday derives from Date, adding a name field representing the person's birthday, e.g.,

```
class Birthday : public Date {
public:
    Birthday (const char *n, int m, int d, int y)
        : Date (m, d, y), person_ (strdup (n)) {}
        "Birthday (void) { free (person_); }
        virtual void print (ostream &s) const;
        // ...
private:
        const char *person_;
};
```

# **Implementation and Use-case**

• Birthday::print could print the person's name as well as the date, *e.g.*,

```
void Birthday::print (ostream &s) const {
    s << this->person_ << " was born on ";
    Date::print (s);
    s << "\n";
}</pre>
```

```
• e.g.,
```

```
const Date july_4th (7, 4, 1993);
Birthday my_birthday ("Douglas C. Schmidt", 7, 18, 1962);
```

```
july_4th.print (cerr);
// july 4th, 1993
my_birthday.print (cout);
// Douglas C. Schmidt was born on july 18th, 1962
Date *dp = &my_birthday;
dp->print (cerr);
// ??? what gets printed ???
// (*dp->vptr[1])(dp, cerr);
```

# Alternatives to Specialization

• Note that we could also use *object composition* instead of *inheritance* for this example, *e.g.*,

```
class Birthday {
public
    Birthday (char *n, int m, int d, int y):
        date_ (m, d, y), person_ (n) {}
    // same as before
private:
    Date date_;
    char *person_;
};
```

 However, in this case we would not be able to utilize the dynamic binding facilities for base classes and derived classes

— e.g.,

Date \*dp = &my\_birthday;

- // ERROR, Birthday is not a subclass of date!
- While this does not necessarily affect reusability, it does affect extensibility...

# Using Inheritance for Extension/Generalization

- Derived classes add state variables and/or operations to the properties and operations associated with the base class
  - Note, the interface is generally widened!
  - Data member and method access privileges may also be modified
- Extension/generalization is often used to faciliate reuse of *implementations*, rather than *interface* 
  - However, it is not always necessary or correct to export interfaces from a base class to derived classes

# Extension/Generalization Example

• Using class Vector as a private base class for derived class Stack

class Stack : private Vector { /\* ...\*/ };

- In this case, Vector's operator[] may be reused as an implementation for the Stack push and pop methods
  - Note that using private inheritance ensures that operator [] does not show up in the interface for class Stack!
- Often, a better approach in this case is to use a composition/Has-A rather than a descendant/Is-A relationship...

## **Vector Interface**

- Using class Vector as a base class for a derived class such as class Checked\_Vector or class Ada\_Vector
  - One can define a Vector class that implements an unchecked, uninitialized array of elements of type T
- e.g., /\* File Vector.h (incomplete wrt initialization and assignment) \*/

};

# **Vector Implementation**

#### • e.g.,

```
template <class T>
Vector<T>::Vector (size_t s): size_ (s), buf_ (new T[s]) {}
```

```
template <class T>
Vector<T>::~Vector (void) { delete [] this->buf_; }
```

template <class T> size\_t
Vector<T>::size (void) const { return this->size\_; }

```
template <class T> T &
Vector<T>::operator[] (size_t i) { return this->buf_[i]; }
```

```
int main (void) {
    Vector<int> v (10);
    v[6] = v[5] + 4; // oops, no initial values
    int i = v[v.size ()]; // oops, out of range!
    // destructor automatically called
}
```

# **Benefits of Inheritance**

- Inheritance enables modification and/or extension of ADTs without changing the original source code
  - *e.g.*, someone may want a variation on the basic Vector abstraction:
    - 1. A vector whose bounds are checked on every reference
    - 2. Allow vectors to have lower bounds other than 0
    - 3. Other vector variants are possible too...
      - \* *e.g.*, automatically-resizing vectors, initialized vectors, etc.
- This is done by defining new derived classes that inherit the characteristics of the Vector base class
  - Note that inheritance also allows code to be shared

# Checked\_Vector Interface

- The following is a subclass of Vector that allows run-time range checking:
- /\* File Checked-Vector.h (incomplete wrt initialization and assignment) \*/

```
struct RANGE_ERROR {
    "range_error" (size_t index);
    // ...
};
template <class T>
class Checked_Vector : public Vector<T> {
    public:
        Checked_Vector (size_t s);
        T &operator[] (size_t i) throw (RANGE_ERROR);
        // Vector::size () inherited from base class Vector.
protected:
        bool in_range (size_t i) const;
private:
        typedef Vector<T> inherited;
};
```

# Implementation of Checked\_Vector

```
• e.g.,
```

```
template <class T> bool
Checked_Vector<T>::in_range (size_t i) const {
    return i < this->size ();
}
```

```
template <class T>
Checked_Vector<T>::Checked_Vector (size_t s)
        : inherited (s) {}
```

```
template <class T> T &
Checked_Vector<T>::operator[] (size_t i)
    throw (RANGE_ERROR)
{
```

```
if (this->in_range (i))
    return (*(inherited *) this)[i];
    // return BASE::operator[](i);
else
```

```
throw RANGE_ERROR (i);
```

}

# Checked\_Vector Use-case

• e.g.,

#include "Checked\_Vector.h"

typedef Checked\_Vector<int> CV\_INT;

# Design Tip

- Note, dealing with parent and base classes
  - It is often useful to write derived classes that do not encode the names of their direct parent class or base class in any of the method bodies
  - Here's one way to do this systematically:

```
class Base {
  public:
       int foo (void);
  };
  class Derived_1 : public Base {
       typedef Base inherited;
  public:
       int foo (void) { inherited::foo (); }
  };
  class Derived_2 : public Derived_1 {
       typedef Derived_1 inherited;
  public:
       int foo (void) {
            inherited::foo ();
       }
  };
- This scheme obviously doesn't work as trans-
  parently for multiple inheritance...
```

# Ada\_Vector Interface

- The following is an Ada Vector example, where we can have array bounds start at something other than zero
- /\* File ada\_vector.h (still incomplete wrt initialization and assignment....) \*/

```
#include "vector.h"
// Ada Vectors are also range checked!
template <class T>
class Ada_Vector : private Checked_Vector<T> {
public:
        Ada_Vector (size_t I, size_t h);
        T &operator ()(size_t i) throw (RANGE_ERROR)
        inherited::size; // explicitly extend visibility
private:
        typedef Checked_Vector<T> inherited;
        size_t lo_bnd_;
};
```

# **Ada\_Vector Implementation**

• *e.g.*, class Ada\_Vector (cont'd)

```
template <class T>
Ada_Vector<T>::Ada_Vector (size_t lo, size_t hi)
            : inherited (hi - lo + 1), lo_bnd_ (lo) {}
```

```
template <class T> T &
Ada_Vector<T>::operator ()(size_t i)
throw (RANGE_ERROR) {
if (this->in_range (i - this->lo_bnd_))
return Vector<T>::operator[] (i - this->lo_bnd_);
// or Vector<T> &self = *(Vector<T> *) this;
// self[i - this->lo_bnd_];
else
throw RANGE_ERROR (i);
}
```

## Ada\_Vector Use-case

• Example Ada Vector Usage (File main.C)

```
#include <iostream.h>
#include <stdlib.h>
#include "ada_vector.h"
int main (int argc, char *argv[]) {
    try {
          size_t lower = ::atoi (argv[1]);
          size_t upper = ::atoi (argv[2]);
          Ada_Vector<int> ada_vec (lower, upper);
          ada_vec (lower) = 0;
         for (size_t i = lower + 1; i <= ada_vec.size (); i++)</pre>
              ada_vec (i) = ada_vec (i - 1) + 1;
          // Run-time error, index out of range
          ada_vec (upper + 1) = 100;
          // Vector destructor called when
          // ada_vec goes out of scope
     }
     catch (RANGE_ERROR) { /* ... */ }
}
```

## Memory Layout

 Memory layouts in derived classes are created by concatenating memory from the base class(es)

```
- e.g., // from the cfront-generated .c file
```

```
struct Vector {
    T *buf__6Vector;
    size_t size__6Vector;
};
struct Checked_Vector {
    T *buf__6Vector;
    size_t size__6Vector;
};
struct Ada_Vector {
    T *buf__6Vector; // Vector
    size_t size__6Vector; // part
    size_t lo_bnd__10Ada_Vector; // Ada_Vector
};
```

• The derived class constructor calls the base constructor in the "base initialization section," *i.e.*,

```
Ada_Vector<T>::Ada_Vector (size_t lo, size_t hi)
: inherited (hi - lo + 1), lo_bnd_ (lo) {}
_{35}
```

# **Base Class Constructor**

- Constructors are called from the "bottom up"
- Destructors are called from the "top down"
- e.g.,

```
/* Vector constructor */
struct Vector *
__ct__6VectorFi (struct Vector *__0this, size_t __0s) {
    if (__0this || (__0this =
        __nw__FUi (sizeof (struct Vector))))
        ((__0this->size__6Vector = __0s),
        (__0this->buf__6Vector =
        __nw__FUi ((sizeof (int)) * __0s)));
    return __0this;
}
```

# **Derived Class Constructors**

#### • e.g.,

```
/* Checked_Vector constructor */
struct Checked_Vector *__ct__14Checked_VectorFi (
     struct Checked_Vector *__0this, size_t __0s) {
    if (__0this || (__0this =
          __nw__FUi (sizeof (struct Checked_Vector))))
          __Othis = __ct__6VectorFi (__Othis, __Os);
    return __0this;
}
/* Ada_Vector constructor */
struct Ada_Vector *__ct__10Ada_VectorFiT1 (
    struct Ada_Vector *__0this, size_t __0lo, size_t __0hi) {
    if (___0this || (___0this =
         __nw__FUi (sizeof (struct Ada_Vector))))
         if (((__0this = __ct__14Checked_VectorFi (__0this,
              \_0hi - \_0lo + 1)))
              __Othis->lo_bnd__10Ada_Vector = __Olo;
    return __Othis;
}
```

## Destructor

- Note, destructors, constructors, and assignment operators are *not* inherited
- However, they may be called automatically were necessary, *e.g.*,

```
char __dt__6VectorFv (
    struct Vector *__0this, int __0__free) {
    if (__0this) {
        __dl__FPv ((char *) __0this->buf__6Vector);
        if (__0this)
            if (__0__free & 1)
              __dl__FPv ((char *) __0this);
    }
}
```

# Describing Relationships Between Classes

- Consumer/Composition/Aggregation
  - A class is a consumer of another class when it makes use of the other class's services, as defined in its interface
    - \* For example, a Stack implementation could rely on an array for its implementation and thus be a consumer of the Array class
  - Consumers are used to describe a Has-A relationship
- Descendant/Inheritance/Specialization
  - A class is a descendant of one or more other classes when it is designed as an extension or specialization of these classes. This is the notion of inheritance
  - Descendants are used to describe an *Is-A* relationship





# Interface vs. Implementation Inheritance

- Class inheritance can be used in two primary ways:
  - 1. *Interface inheritance*: a method of creating a subtype of an existing class for purposes of setting up dynamic binding, *e.g.*,
    - Circle is a subclass of Shape (*i.e.*, *Is-A* relation)
    - A Birthday is a subclass of Date
  - 2. *Implementation inheritance*: a method of reusing an implementation to create a new class type
    - *e.g.*, a **class** Stack that inherits from **class** Vector. A Stack is not really a subtype or specialization of Vector
    - In this case, inheritance makes implementation easier, since there is no need to rewrite and debug existing code.
      - \* This is called "using inheritance for reuse"
      - \* *i.e.*, a pseudo-*Has*-A relation

# The Dangers of Implementation Inheritance

- Using inheritance for reuse may sometimes be a dangerous misuse of the technique
  - Operations that are valid for the base type may not apply to the derived type at all
    - *e.g.*, performing an subscript operation on a stack is a meaningless and potentially harmful operation

```
class Stack : public Vector {
    // ...
};
Stack s;
s[10] = 20; // could be big trouble!
```

- In C++, the use of a private base class minimizes the dangers
  - *i.e.*, if a class is derived "private," it is illegal to assign the address of a derived object to a pointer to a base object
- On the other hand, a consumer/Has-A relation might be more appropriate...

# Private vs Public vs Protected Derivation

- Access control specifiers (*i.e.*, public, private, protected) are also meaningful in the context of inheritance
- In the following examples:
  - <....> represents actual (omitted) code
  - [....] is implicit
- Note, all the examples work for both data members and methods

## **Public Derivation**

• e.g.,

class A {
public:
 <public A>
protected:
 <protected A>
private:
 <private A>
};

class B : public A {
public:
 [public A]
 <public B>
protected:
 [protected A]
 <protected B>
private:
 <private B>
};

## **Private Derivation**

• e.g.,

class A {
public:
 <public A>
private:
 <private A>
protected:
 <protected A>
};

## **Protected Derivation**

• e.g.,

class B : protected A {
public:
 <public B>
protected:
 [protected A]
 [public A]
 <protected B>
private:
 <private B>
};

## Summary of Access Rights

- The following table describes the access rights of inherited methods
  - The vertical axis represents the access rights of the methods of base class
  - The horizontal access represents the mode of inheritance



 Note that the resulting access is always the most restrictive of the two

# Other Uses of Access Control Specifiers

• Selectively redefine visibility of individual methods from base classes that are derived *privately* 

```
class A {
public:
    int f ();
    int g_;
    ...
private:
    int p_;
};
class B : private A {
public:
    A::f; // Make public
protected:
    A::g_; // Make protected
};
```

# Common Errors with Access Control Specifiers

- It is an error to "increase" the access of an inherited method in a derived class
  - e.g., you may not say:

```
class B : private A {
  // nor protected nor public!
  public:
        A::p_; // ERROR!
};
```

 It is also an error to derive *publically* and then try to selectively decrease the visibility of base class methods in the derived class

- e.g., you may not say:

```
class B : public A {
private:
    A::f; // ERROR!
};
```

# General Rules for Access Control Specifiers

- Private methods of the base class are not accessible to a derived class (unless the derived class is a **friend** of the base class)
- If the subclass is derived *publically* then:
  - 1. Public methods of the base class are accessible to the derived class
  - 2. Protected methods of the base class are accessible to derived classes and friends only

# Caveats

• Using protected methods weakens the data hiding mechanism since changes to the base class implementation might affect all derived classes. *e.g.*,

```
class Vector {
public:
    //...
protected:
// allow derived classes direct access
    T *buf_;
    size_t size_;
};
class Ada_Vector : public Vector {
public:
    T & operator() (size_t i) {
        return this->buf_[i];
        }
        // Note the strong dependency on the name buf_
};
```

- However, performance and design reasons may dictate use of the protected access control specifier
  - Note, inline functions often reduces the need for these efficiency hacks...

# Overview of Multiple Inheritance in C++

- C++ allows *multiple inheritance* 
  - *i.e.*, a class can be simultaneously derived from two or more base classes
  - e.g.,
    - class X { /\* .... \*/ }; class Y : public X { /\* .... \*/ }; class Z : public X { /\* .... \*/ }; class YZ : public Y, public Z { /\* .... \*/ };
  - Derived classes Y, Z, and YZ inherit the data members and methods from their respective base classes



# **Liabilities of Multiple Inheritance**

- A base class may legally appear only once in a derivation list, *e.g.*,
  - class Two\_Vector : public Vector, public Vector // ERROR!
- However, a base class may appear multiple times within a derivation hierarchy
  - e.g., class YZ contains two instances of class X
- This leads to two problems with multiple inheritance:
  - 1. It gives rise to a form of method and data member ambiguity
    - Explicitly qualified names and additional methods are used to resolve this
  - 2. It also may cause unnecessary duplication of storage
    - "Virtual base classes" are used to resolve this

# Motivation for Virtual Base Classes

• Consider a user who wants an Init\_Checked\_Vector:

class Checked\_Vector : public virtual Vector
{ /\* .... \*/ };
class Init\_Vector : public virtual Vector
{ /\* .... \*/ };
class Init\_Checked\_Vector :
 public Checked\_Vector, public Init\_Vector
{ /\* .... \*/ };

 In this example, the virtual keyword, when applied to a base class, causes Init\_Checked\_Vector to get one Vector base class instead of two

# **Overview of Virtual Base Classes**

- Virtual base classes allow class designers to specify that a base class will be shared among derived classes
  - No matter how often a virtual base class may occur in a derivation hierarchy, only "one" shared instance is generated when an object is instantiated
    - Under the hood, pointers are used in derived classes that contain virtual base classes
- Understanding and using virtual base classes correctly is a non-trivial task since you must plan in advance
  - Also, you must be aware when initializing subclasses objects...
- However, virtual base classes are used to implement the client and server side of many implementations of CORBA distributed objects



## **Initializing Virtual Base Classes**

- With C++ you must chose one of two methods to make constructors work correctly for virtual base classes:
  - 1. You need to either supply a constructor in a virtual base class that takes no arguments (or has default arguments), *e.g.*,

Vector::Vector (size\_t size = 100); // has problems...

2. Or, you must make sure the *most derived class* calls the constructor for the virtual base class in its *base initialization section*, *e.g.*,

Init\_Checked\_Vector (size\_t size, const T &init):
 Vector (size), Check\_Vector (size),
 Init\_Vector (size, init)

# Vector Interface Revised

 The following example illustrates templates, multiple inheritance, and virtual base classes in C++

```
#include <iostream.h>
#include <assert.h>
// A simple-minded Vector base class,
// no range checking, no initialization.
template <class T>
class Vector
{
    public:
        Vector (size_t s): size_ (s), buf_ (new T[s]) {}
        T &operator[] (size_t i) { return this->buf_[i]; }
        size_t size (void) const { return this->size_; }
private:
        size_t size_;
        T *buf_;
};
```

# **Init\_Vector Interface**

 A simple extension to the Vector base class, that enables automagical vector initialization

# **Checked\_Vector Interface**

• A simple extension to the Vector base class that provides range checked subscripting

```
template <class \top >
class Checked_Vector : public virtual Vector<T>
{
public:
     Checked_Vector (size_t size): Vector<T> (size) {}
     T & operator[] (size_t i) throw (RANGE_ERROR) {
         if (this->in_range (i))
              return (*(inherited *) this)[i];
         else throw RANGE_ERROR (i);
     }
     // Inherits inherited::size.
private:
    typedef Vector<T> inherited;
    bool in_range (size_t i) const {
         return i < this->size ();
     }
```

};

# Init\_Checked\_Vector Interface and

#### Driver

• A simple multiple inheritance example that provides for both an initialized *and* range checked Vector

```
template <class T>
class Init_Checked_Vector :
    public Checked_Vector<T>, public Init_Vector<T> {
    public:
        Init_Checked_Vector (size_t size, const T &init):
            Vector<T> (size),
            Init_Vector<T> (size, init),
            Checked_Vector<T> (size) {}
        // Inherits Checked_Vector::operator[]
};
```

• Driver program

```
int main (int argc, char *argv[]) {
    try {
        size_t size = ::atoi (argv[1]);
        size_t init = ::atoi (argv[2]);
        Init_Checked_Vector<int> v (size, init);
        cout << "vector size = " << v.size ()
            << ", vector contents = ";
        for (size_t i = 0; i < v.size (); i++)
            cout << v[i];
        cout << "\n" << ++v[v.size () - 1] << "\n";
        catch (RANGE_ERROR) { /* ...*/ }
}</pre>
```

# Multiple Inheritance Ambiguity

• Consider the following:

```
struct Base_1 { int foo (void); /* .... */ };
struct Base_2 { int foo (void); /* .... */ };
struct Derived : Base_1, Base_2 { /* .... */ };
int main (void) {
    Derived d;
    d.foo (); // Error, ambiguous call to foo ()
}
```

- There are two ways to fix this problem:
  - 1. Explicitly qualify the call, by prefixing it with the name of the intended base class using the scope resolution operator, *e.g.*,

```
d.Base_1::foo (); // or d.Base_2::foo ()
```

2. Add a new method foo to class Derived (similar to Eiffel's renaming concept) *e.g.*,

```
struct Derived : Base_1, Base_2 {
    int foo (void) {
        Base_1::foo (); // either, both
        Base_2::foo (); // or neither
    }
};
```

# Summary

- Inheritance supports evolutionary, incremental development of reusable components by specializing and/or extending a general interface/implementation
- Inheritance adds a new dimension to data abstraction, *e.g.*,
  - Classes (ADTs) support the expression of *commonality* where the *general* aspects of an application are encapsulated in a few *base classes*
  - Inheritance supports the development of the application by *extension* and *specialization* without affecting existing code...
- Without browser support, navigating through complex inheritance hierarchies is difficult...